



# Development of sensors systems for detecting impacts on road safety barriers Antonio Astuti

Pillar SMART MOBILITY – Spoke 7 / WP2

### **SAMOTHRACE** 2<sup>nd</sup> Year:

Experimental Prototypes Demo Showcase

SAMOTHRACE PROJECT ECS00000022

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### samothrace Addressing the Wildfire Challenge: Needs, Limitations and Market Opportunity MERID



#### **Problem Definition and Market Need**

The developed innovation aims to improve road safety through timely and accurate monitoring of impacts on guardrails, overcoming the limitations of current solutions based on manual reports or periodic inspections, which cause delays in interventions.

#### **Target Audience and Unmet Need**

The system is primarily intended for road infrastructure management entities, transport sector operators, and public administrations responsible for road maintenance.

#### **Limitations of Existing Solutions**

Current solutions have limitations such as non-real-time monitoring and high installation and maintenance costs due to the need for expensive infrastructure and complex wiring.

#### **Market Opportunities**

The market for road safety systems is growing, driven by the need to reduce accidents and improve infrastructure management. The smart road sector is expected to expand further, supported by investments and the availability of low-cost components, making these solutions highly scalable for large-scale implementation.









### Real-Time Guardrail Impact Detection System



The developed system offers an innovative solution for real-time impact monitoring on guardrails, overcoming limitations of traditional technologies. It uses high-sensitivity, low-power MEMS sensors installed in the guardrail bolts, enabling discreet and effective detection. When an impact occurs, the system immediately processes and transmits the data to a wide-coverage network for prompt alerts. With energy autonomy through an integrated solar panel, the system eliminates the need for external power, reducing installation and maintenance costs, making it ideal for quick deployment.











### Development plan under SAMOTHRACE Ecosystem



In the initial phase (TRL 3), the technology was tested in the laboratory with MEMS sensors to detect impacts.

Thanks to SAMOTHRACE funding, significant milestones were achieved:

- Innovative monitoring system
- Energy autonomy
- Validated and field-tested

These advancements have brought the technology to **TRL 5**, with real-world tests confirming its effectiveness compared to traditional solutions, thanks to collaboration with **ANAS SpA**.















### Next step under SAMOTHRACE Ecosystem



The final goal is to reach **TRL 7** by the end of the project.

To achieve this milestone, the following progress will be necessary:

- System optimization
- Large-scale testing
- Integration with Smart Road Systems

With these advancements, the project will be ready to demonstrate its full operational capacity, thus reaching TRL 7.















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## VISIT OUR DEMO AT BOOTH N. 72

### **Demo location:**

 Belpasso (CT), Bivio Aspro Zona, Industriale Piano Tavola





